



**Institute of Automation and Information Technologies  
Department "Automation and control"**

**EDUCATIONAL PROGRAM  
7M07114 - AUTOMATION AND ROBOTIZATION**  
code and name of the educational program

Code and classification of the field of education: **7M07 Engineering, manufacturing and construction industries**

Code and classification of areas of study: **7M071 Engineering and Engineering affairs**

Group of educational programs: **M100 Automation and management**

NQF level: **7**

ORC level: **7**

Duration of study: **1.5 years**

Volume of credits: **90 credits**

**Almaty 2025**




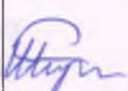
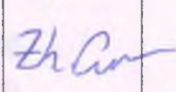
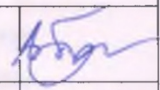
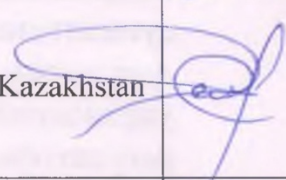
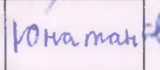

The education program **“7M07114 – Automation and robotization”** was approved at a meeting of the Academic Council of KazNITU named after K. I. Satbayev.

Protocol №10 «06» March 2025 y.

Reviewed and recommended for approval at the meeting of the Teaching and Methodological Council of KazNITU named after K. I. Satbayev.

Protocol №3 «20» December 2024 y.

The educational program **«7M07114 – Automation and robotization»** has been developed by the academic committee of **«7M071 Engineering and Engineering affairs»**.

| Full name                                  | Scientific degree / Academic title | Position  | Workplace  | Caption   |
|--|------------------------------------|---|--|---|
| <b>Chairman of the academic committee:</b> |                                    |   |  |   |
| Sarsenbayev Nurlan                         | Candidate of technical sciences    | Associate professor, head of the department                                 | NAO «Kazakh National Research Technical University named after K. I. Satbayev» |   |
| <b>Teaching staff:</b>                     |                                    |   |  |   |
| Suleymenov Batyrkbek                       | Doctor of technical sciences       | Professor   | NAO «Kazakh National Research Technical University named after K. I. Satbayev» |  |
| Beisembayev Akhambay                       | Candidate of technical sciences    | Associate professor   | NAO «Kazakh National Research Technical University named after K. I. Satbayev» |  |
| Shiryayeva Olga                            | Candidate of technical sciences    | Associate professor   | NAO «Kazakh National Research Technical University named after K. I. Satbayev» |  |
| Omirbekova Zhanar                          | Doctor PhD                         | Associate professor   | NAO «Kazakh National Research Technical University named after K. I. Satbayev» |  |
| <b>Employers:</b>                          |                                    |   |  |   |
| Abdigaliyev Serik                          | APCS engineer                      | General director  | LLP «ACYTII-Honeywell»   |  |
| Saurambayev Zhiger                         | APCS engineer                      | Head of Industrial Automation and Solutions for Kazakhstan and Central Asia | Schneider Electric Kazakhstan  |  |
| Yunatanov Yurii                            | APCS engineer                      | General director  | Process Automation LLP, Kazakhstan   |  |
| <b>Students:</b>                           |                                    |   |  |   |
| Shukenov Zhalgas                           | Master                             | 1 <sup>st</sup> year master's student                                       | -  |  |

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### **List of abbreviations and symbols**

|     |                                |
|-----|--------------------------------|
| EP  | Educational program            |
| LSU | Microprocessor control systems |
| RFP | Application package            |

## 1. Description of the educational program

The educational program (here in after EP) is a set of documents developed by the Kazakh National Research Technical University named after K.I. Satpayev and approved by the Ministry of Education and Science of the Republic of Kazakhstan.

Educational program 7M07114 - «Automatization and Robotization» involves the training of highly qualified specialists in the field of automation, robotics, artificial intelligence and automated control.

The bachelor's degree in the EP «Automatization and Robotization» provides for the acquisition of competencies in a wider area: automation, robotics, artificial intelligence and automated control in order to ensure the adaptation of bachelor's graduates to the requirements of the labor market. This EP of the master's program provides for further deepening of the competencies acquired in the bachelor's degree. In this connection, modern innovative disciplines have been introduced into the program for each of the trajectories.

In the process of mastering the educational program, the Master of Technical Sciences in the field of automation of production processes must acquire the following key competencies:

- will be able to analyze literature data and, on the basis of the analysis, determine and experimentally implement possible ways to modernize automated and robotic systems using new technical solutions.
- will be able to apply appropriate methods of analysis, both qualitative and quantitative, to collect and integrate information in the best possible way.
- will be able to conduct independent original research that contributes to the development of science, in accordance with the best practices and industry standards.
- have the skills to create robotic systems and automated technological complexes.
- have professional knowledge in the field of automation, robotization, artificial intelligence and automated control.

Objects of professional activity:

- automation and process control systems;
- robotic systems and complexes;

The Master in Automation of Production Processes must solve the following tasks in accordance with the types of professional activity:

*in the field of production and technological activities:*

- to be a leading engineer, a leading specialist of the production unit for the operation, maintenance, repair and adjustment of technical means of automated control systems for production processes in various industries;

*in the field of organizational and managerial activities:*

- to be the head of the department for the maintenance and repair of elements, devices of automated control systems for production processes in various industries;

*in the field of experimental research activities:*

- to be a leading specialist in conducting experimental studies of industrial automation objects;

*in the field of research and teaching activities:*

- be a researcher in a scientific laboratory for the research and development of modern automated control systems for production processes in various industries;

*in the field of design activities:*

- be a leading engineer or chief engineer of a project for the development and design of automated control systems for production processes in various industries.

## **2. Purpose and objectives of the educational program**

### **Purpose of the EP:**

Training highly qualified specialists who are proficient in modern methods of automation, robotics, and intelligent control, capable of innovative activities and the development of sustainable technological solutions.

### **Tasks of the EP:**

Based on the achievements of modern science, technology and production, to provide knowledge and skills in the field of:

- automation;
- robotics;
- artificial intelligence;
- automated control.

## **3. Requirements for evaluating the learning outcomes of an educational program**

OP 7MO7114 - «Automatization and Robotization» ensures that all students achieve the learning outcomes necessary for professional activities. At the end of the program, the student must:

- freely use in professional activities of the state, Russian and one of the most common, foreign language.
- master the main methods: data mining, descriptive analysis, correlation and regression analysis, classical calculus of variations, matrix description of spatial mechanisms.
- to master the main methods of modern control theory: synthesis of systems with a given dynamics using standard and relay controllers, digital control systems, systems with variable structure, modal control, identification and adaptation and optimal control.
- freely master the basics of philosophical, pedagogical, economic knowledge.
- possess the skills of describing the kinematics and dynamics of industrial robots, methods of developing software trajectories, developing adaptive and non-adaptive control algorithms for industrial robots.

- to have the skills to create automated process control systems and robotic technological complexes.
- knowledge of modern technical means of automation and robotics. Own the basics of the practical application of modern technical means of automation.
- to possess the skills of building microprocessor systems (MSU). To be able to design hardware and software of MSU.
- possess the skills of software and stabilizing, optimal and adaptive control and synthesis of intelligent control systems.
- to possess the skills to conduct research and design work on the development of automated process control systems and robotic technological systems in various industries.

## 4. Passport of the educational program

### 4.1. General information

| No. | Field name  | Note  |
|-----|---|---|
| 1   | Code and classification of the field of education | 7M07 Engineering, manufacturing and construction industries   |
| 2   | Code and classification of areas of study         | 7M071 Engineering and Engineering affairs   |
| 3   | Group of educational programs                     | M100 Automation and management  |
| 4   | Name of the educational program                   | 7M07114 - Automation and robotization   |
| 5   | Brief description of the educational program      | Educational program 7M07114 - Automatization and robotization involves the training of highly qualified specialists in the field of automation, robotics, artificial intelligence and automated control.  |
| 6   | Purpose of the EP                                 | Training highly qualified specialists who are proficient in modern methods of automation, robotics, and intelligent control, capable of innovative activities and the development of sustainable technological solutions.   |
| 7   | EP type   | New EP  |
| 8   | NQF level   | 7   |
| 9   | ORC level   | 7   |
| 10  | Distinctive features of the EP                    | No  |
| 11  | List of competencies of the educational program:  | <p>In the process of mastering the educational program, the Master of Technical Sciences in the field of automation of production processes must acquire the following key competencies:</p> <ul style="list-style-type: none"> <li>- will be able to analyze literature data and, on the basis of the analysis, determine and experimentally implement possible ways to modernize automated and robotic systems using new technical solutions.</li> <li>- will be able to apply appropriate methods of analysis, both qualitative and quantitative, to collect and integrate information in the best possible way.</li> <li>- will be able to conduct independent original research that contributes to the development of science, in accordance with the best practices and industry standards.</li> <li>- have the skills to create robotic systems and automated technological complexes.</li> <li>- have professional knowledge in the field of automation, robotization, artificial intelligence and automated control.</li> </ul> |
| 12  | Learning outcomes of the educational program:     | <p>LO1 – Be fluent in the basics of psychology, philosophical, pedagogical and economic knowledge.</p> <p>LO2 – Know the basic methods of modern control theory: synthesis of systems with given dynamics using standard and relay controllers, digital control systems, systems with variable structure, modal control, identification and adaptation of optimal control.</p> <p>LO3 – Possess the skills of software and stabilizing, optimal</p>   |



|    |                           |   |
|----|---------------------------|---|
|    |                           | <p>and adaptive control and synthesis of intelligent control systems.</p> <p>LO4 – Possess the skills of conducting research and design work on the development of automated process control systems and robotic technological systems in various industries.</p> <p>LO5 – Possess skills in working with data from automated and robotic production processes, including collecting, processing, analyzing and visualizing data for making operational decisions and optimizing production processes, diagnosing and ensuring the reliability of automation systems.</p> <p>LO6 – Know modern technical means of automation and robotics. Possess the basics of practical application of modern technical automation equipment.</p> <p>LO7 – Designing hardware and software components of microprocessor systems, developing and synthesizing digital, integrated, and distributed control systems, contributing to the development of the digital industry.</p> <p>LO8 – Freely use the state, Russian and one of the common foreign languages in professional activities.</p> <p>LO9 – Mastering the basic methods: intellectual data analysis, descriptive analysis, correlation and regression analysis, classical variational calculus, matrix description of spatial mechanisms.</p> <p>LO10 – The ability to design modern and reliable units and devices, intelligently controlled modules of robotic and automated systems for sustainable production.</p> |
| 13 | Form of study             | full-time   |
| 14 | Training period           | 1.5 years   |
| 15 | Volume of credits         | 90 credits  |
| 16 | Languages of instruction  | Kazakh, Russian   |
| 17 | Awarded Academic Degree   | Master of Engineering   |
| 18 | Developer(s) and authors: | Aldiyarov N.U., Manatov K. A.   |

## 4.2. The relationship between the achievability of the formed learning outcomes in the educational program and academic disciplines

| No.  | Name of the discipline                          | Brief description of the discipline   | Amount of credits | Formed learning outcomes (codes) |     |     |     |     |     |     |     |     |      |
|--|---|---|-------------------|----------------------------------|-----|-----|-----|-----|-----|-----|-----|-----|------|
|  |   |   |                   | LO1                              | LO2 | LO3 | LO4 | LO5 | LO6 | LO7 | LO8 | LO9 | LO10 |
| Cycle of basic disciplines<br>University component |   |   |                   |                                  |     |     |     |     |     |     |     |     |      |
| 1  | Foreign language (professional)                 | The purpose of the discipline is to acquire and improve competencies in accordance with trade standards of foreign education, capable of competing in the labor market, because through a foreign language, the future master gains access to academic knowledge, new technologies and modern information, allowing the use of a foreign language as a means of communication in the intercultural, professional and scientific activities of the future master.        | 2                 |                                  |     |     |     |     |     |     | V   |     |      |
| 2  | Management                                      | Purpose: To form a scientific understanding of management as a type of professional activity. Contents: Mastering the general theoretical principles of managing socio-economic systems; acquiring skills and abilities in practical problem-solving of managerial issues; studying global management practices and the specificities of Kazakhstani management; training in solving practical issues related to managing various aspects of organizational activities. | 2                 | V                                |     |     |     |     |     |     |     |     |      |
| 3  | Psychology of management                        | Objective: To acquire skills in making strategic and managerial decisions, taking into account the psychological characteristics of the individual and the team. Content: the modern role and content of psychological aspects in management activities, methods for improving psychological literacy, the composition and structure of management activities, both at the local and foreign levels, the psychological feature of modern managers.                      | 2                 | V                                |     |     |     |     |     |     |     |     |      |
| Cycle of basic disciplines<br>Selectable Component |   |   |                   |                                  |     |     |     |     |     |     |     |     |      |
| 4  | Integrated automation technology and management | The task of studying the discipline is to acquire knowledge on effective technologies for modeling automation objects, to study the directions of development of automation tools, fundamentally new methods of process control, computer-integrated production of a new generation, as well as to acquire skills in forming a production   | 4                 |                                  |     |     |     |     | V   |     |     | V   |      |

NJSC "Kazakh National RESEARCH Technical University"  
named after K.I. Satpayev"

|  |                                    |   |   |  |   |  |   |  |  |   |   |   |   |
|--|------------------------------------|---|---|--|---|--|---|--|--|---|---|---|---|
|  |                                    | automation strategy, the use of modern automation devices to solve control problems, the formation of sets of modern sensors and converters to combine them into a computer-integrated production system.   |   |  |   |  |   |  |  |   |   |   |   |
| 5  | Intelligent technology in robotics | The course "Intelligent technologies in robotics" discusses the main characteristics of robots: load capacity, coordinate movement system, the number of degrees of mobility; the speed of movement and the magnitude of the stroke of each link, the positioning error, the method of installation in the workplace, the working service area. Classification and principles of construction of robotic systems. Technological requirements for robotic systems used in enterprises. An actively developing field of artificial intelligence. It includes models, methods and algorithms focused on automatic accumulation and formation of knowledge based on data analysis and generalization. It includes example-based (or inductive) learning, as well as traditional approaches from pattern recognition theory. | 5 |  | V |  |   |  |  |   | V |   |   |
| 6  | Data Mining Methods                | The discipline considers the most common methods and algorithms of data mining. Special attention is paid to understanding the principles and concepts underlying modern intellectual methods. Using practical examples, the features of data analysis when conducting research in the field of automation and control are considered.  | 5 |  |   |  |   |  |  |   |   | V | V |
| 7  | Modern control theory              | The content of the discipline includes the study of modern approaches for the analysis and synthesis of automatic control systems based on the "state space" methodology. The properties of linear and nonlinear systems and methods for their study are considered from a unified positions of the state space method. Provided basic information about systems with variable structure, modal control, identification, adaptation and optimization in control systems.  | 4 |  |   |  | V |  |  |   |   | V |   |
| 8  | Sustainable development strategies | Purpose: To train graduate students in sustainable development strategies to achieve a balance between economic growth, social responsibility, and environmental protection. Content: Graduate students will study the concepts and principles of sustainable development, the development and implementation of sustainable development strategies, the evaluation of their effectiveness, and international standards and best practices. Cases and examples of successful sustainable development strategies are included.   | 5 |  |   |  |   |  |  | V |   |   | V |
| <b>Cycle of major disciplines<br/>University component</b> |                                    |   |   |  |   |  |   |  |  |   |   |   |   |

|  |   |   |   |   |   |  |  |   |   |   |   |  |  |   |
|--|---|---|---|---|---|--|--|---|---|---|---|--|--|---|
| 9  | Automation of engineering systems                               | The content of the discipline includes the methodological foundations for creating an automated system for technological preparation of production (APS). Taking into account the trends in the development of modern industrial production and new information technologies for its automation, the main principles for building the architecture of an IT system are formulated.  | 5 |   |   |  |  | V |   | V | V |  |  |   |
| 10   | Complex control systems   | The objective of studying the discipline is to acquire knowledge of modern automation technologies and control of real multidimensional and multi-connected complex systems with several adjustable circuits, as well as to acquire skills in developing a production automation strategy, using modern automation devices to solve problems of controlling complex systems, solving modeling and analysis problems and synthesis of complex control systems. The purpose of teaching the discipline is to study modern methods and principles of managing complex, multidimensional and multi-connected systems.   | 4 | V |   |  |  |   |   | V |   |  |  |   |
| <b>Cycle of major disciplines<br/>Selectable Component</b> |   |   |   |   |   |  |  |   |   |   |   |  |  |   |
| 11   | Automation of control systems design                            | The content of the discipline "Automation of control systems design" includes the study of methods of analysis and synthesis of control systems, the choice of structure and the calculation of parameters of the control law. The procedures of analytical design of regulators, development of structural, functional and other automation schemes with the use of modern application software packages are considered.   | 5 |   | V |  |  | V |   |   |   |  |  |   |
| 12   | Automated projection of robotic systems                         | The course "Automated projection of robotic systems" examines the training of specialists who know the theoretical foundations of control system design and methods of performing experimental and computational work on the creation and operation of automation systems based on modern software and hardware.  | 5 |   |   |  |  |   | V |   |   |  |  | V |
| 13   | Machine Learning Algorithms in Technological Process Automation | COURSE AIM AND OBJECTIVES The purpose of the discipline is to study methods of machine learning and analysis of big data for making management decisions in automated control systems of technological processes. The course focuses on determining the key variables of technological processes, identifying their interdependence and their impact on qualitative and quantitative indicators of production. Processing and analysis of large amounts of technological data. Particular attention is paid to machine learning algorithms that allow you to establish complex technological relationships without building complex mathematical models in conditions of uncertainty. | 5 |   | V |  |  | V |   |   |   |  |  |   |

|    |   |  |   |   |  |   |  |   |   |  |  |  |   |  |
|----|---|--|---|---|--|---|--|---|---|--|--|--|---|--|
| 14 | Machine Learning Algorithms in Equipment Condition Diagnostic Systems | The purpose of the discipline is to analyze technological equipment in terms of diagnosing its condition and studying methods of machine learning and big data analysis to solve problems related to the identification of the technical condition of equipment. The course deals with the development of modern systems of equipment condition identification and strategies for maintenance and repair of equipment - according to the actual state. These systems are based on machine learning (ML) algorithms. Within the framework of the course the possibility of application of modern ML algorithms for equipment diagnostics, such as Decision Tree, Random Forest and others is considered. Python programming language is used to implement these algorithms. | 5 |   |  |   |  |   | V |  |  |  |   |  |
| 15 | Diagnostics of system automation                                      | The content of the discipline includes the characteristics of qualitative and quantitative indicators of the reliability of technical systems, their probabilistic and statistical evaluation based on test results, the analysis of the need and the choice of the redundancy rate, consideration of methods and models of technical diagnostics of automation systems.   | 5 |   |  | V |  | V |   |  |  |  |   |  |
| 16 | Dynamics of robot control   | The content of the discipline "Dynamics of robots control" includes the study of mathematical approaches for cyclic, positional and contour control of industrial robots, models and algorithms for kinematic and dynamic analysis of industrial robots, studies of the kinematics and dynamics of the manipulator and drive system of an industrial robot.  | 5 |   |  |   |  |   |   |  |  |  | V |  |
| 17 | The reliability of the management system and its elements             | The discipline "Reliability of the control system and its elements" examines the basic terms, definitions and concepts in the theory of reliability, quantitative indicators of the reliability of renewable and non-renewable technical systems, the main methods for calculating the reliability of complex systems, types of tests for reliability, backup issues and determining the reliability of backup systems. To consolidate the theoretical materials, standard tasks are presented. As well as issues of reliability of automation and control systems.  | 5 |   |  |   |  |   | V |  |  |  |   |  |
| 18 | New information technologies  | The course "New Information Technologies" discusses fundamental problems and mathematical methods of systems theory, characteristics of the stages of system analysis, system analysis procedures, data collection on the functioning of the system, the study of information flows, the construction of models of systems, checking the adequacy of models, uncertainty and sensitivity analysis, the study of resource capabilities, determining the goals of system analysis, the formation of criteria, generating alternatives, the implementation of choice and decision-making; Models of   | 5 | V |  |   |  |   |   |  |  |  |   |  |

|    |  |   |   |  |   |   |   |   |   |  |   |   |  |
|----|--|---|---|--|---|---|---|---|---|--|---|---|--|
|    |  | complex systems; Classification of types of modeling of complex systems, principles and approaches to the construction of mathematical models, stages of building a mathematical model, methods of qualitative evaluation of systems, methods of quantitative evaluation of systems, decision-making in conflict, risk, uncertainty, intelligent models in management.  |   |  |   |   |   |   |   |  |   |   |  |
| 19 | Automation systems design                  | In the discipline, the stages of designing process control systems are studied. Methods of preparation of project documentation in accordance with modern international standards; methods of automating the construction of mathematical models, analysis and synthesis systems using modern computer technologies and automation of scientific research; trends in the development of science and technology and their impact on automation; The essence of a systematic approach in the design of modern hardware and software computing.                                      | 5 |  |   |   |   |   | V |  |   |   |  |
| 20 | Project Management                         | Goal: Gaining knowledge about the components and methods of project management based on modern models and standards. Objectives: study of behavioral models of project-oriented management of business development; mastering international standards PMI PMBOK, IPMA ICB and national standards of the Republic of Kazakhstan in the field of project management; analysis of the features of organizational management of business development through the integration of strategic, project and operational management.  | 5 |  |   |   |   | V |   |  | V |   |  |
| 21 | Distributed Control Systems                | The content of the discipline "Distributed control systems" deals with the choice of structure and composition of hardware and software for distributed control systems. A distributed control system (DCS, DCS - Distributed Control System) can be defined as a system consisting of many devices spaced apart in space, each of which is independent of the others, but interacts with them to perform a common task. The maximum benefits of a distributed system are achieved when controllers work autonomously, and the exchange of information between them is minimized. | 5 |  |   | V |   |   | V |  |   |   |  |
| 22 | Optimal control systems (with AI elements) | The content of the discipline "Optimal control systems" includes the study of mathematical methods of optimal control based on classical calculus of variations, the basics of the maximum principle and the method of dynamic programming. Models and methods of program and stabilizing optimal control are considered. Methods of synthesis of intelligent optimal control systems are considered separately.  | 5 |  |   |   |   |   |   |  |   | V |  |
| 23 | Technical Vision system                    | In the discipline "Systems of technical vision", the main types of technical vision systems used in real-time control systems, the  | 5 |  | V |   | V |   |   |  |   |   |  |

|    |  |   |   |  |   |   |   |  |  |  |  |  |  |
|----|--|---|---|--|---|---|---|--|--|--|--|--|--|
|    |  | features of hardware and software technical vision, methods of organizing and conducting experimental research in the field of technical vision systems are considered. The methods of processing and transformation of inventions are being studied.   |   |  |   |   |   |  |  |  |  |  |  |
| 24 | Modern executive devices of automation systems | The course content discusses general issues of the theory of automation actuators, outlines the principles of classification of actuators and their main characteristics, as well as issues related to actuators as an element of an automation system. The main purpose of the training is to teach the ability to correctly select installation devices in automation systems                                 | 5 |  | V |   | V |  |  |  |  |  |  |
| 25 | Digital control systems                        | The content of the discipline "Digital Control Systems" includes the study of the mathematical apparatus for describing digital systems, describing digital systems in the time and frequency domains, and synthesizing digital controllers in the automation of production processes. Obtaining knowledge about the principles of construction and features of the use of digital control systems in industry. | 5 |  |   | V | V |  |  |  |  |  |  |

## 5. Curriculum of the educational program

NON-PROFIT JOINT STOCK COMPANY  
"KAZAKH NATIONAL RESEARCH TECHNICAL UNIVERSITY NAMED AFTER K.I. SATPAYEV"



«APPROVED»  
Decision of the Academic Council  
NPJSC «KazNRTU»  
named after K.Satbayev»  
dated 06.03.2025 Minutes № 10

### WORKING CURRICULUM

Academic year

Group of educational programs

Educational program

The awarded academic degree

Form and duration of study

2025-2026 (Autumn, Spring)

M100 - "Automation and management"

7M07114 - "Automation and robotization"

Master of engineering and technology

full time (professional track) - 1,5 years

| Discipline code                                      | Name of disciplines   | Block | Cycle   | Total ECTS credits | Total hours | lek/lab/pr Contact hours | in hours SIS (including TSIS) | Form of control | Allocation of face-to-face training based on courses and semesters |       |          | Prerequisites |
|--|---|-------|---------|--------------------|-------------|--------------------------|-------------------------------|-----------------|--|-------|----------|---------------|
|  |   |       |         |                    |             |                          |                               |                 | 1 course   |       | 2 course |               |
|  |   |       |         |                    |             |                          |                               |                 | 1 sem  | 2 sem | 3 sem    |               |
| CYCLE OF GENERAL EDUCATION DISCIPLINES (GED)         |   |       |         |                    |             |                          |                               |                 |  |       |          |               |
| CYCLE OF BASIC DISCIPLINES (BD)                      |   |       |         |                    |             |                          |                               |                 |  |       |          |               |
| M-1. Module of basic training (university component) |   |       |         |                    |             |                          |                               |                 |  |       |          |               |
| MNG726   | Management  |       | BD, UC  | 2                  | 60          | 15/0/15                  | 30                            | E               | 2  |       |          |               |
| HUM211   | Psychology of management  |       | BD, UC  | 2                  | 60          | 15/0/15                  | 30                            | E               | 2  |       |          |               |
| LNG212   | Foreign language (professional)                                       |       | BD, UC  | 2                  | 60          | 0/0/30                   | 30                            | E               | 2  |       |          |               |
| M-2. Module of theoretical foundations of management |   |       |         |                    |             |                          |                               |                 |  |       |          |               |
| AUT711   | Modern control theory   | 1     | BD, CCH | 4                  | 120         | 30/0/15                  | 75                            | E               | 4  |       |          |               |
| AUT712   | Integrated automation technology and management                       | 1     | BD, CCH | 4                  | 120         | 30/0/15                  | 75                            | E               | 4  |       |          |               |
| AUT266   | Data Mining Methods   | 2     | BD, CCH | 5                  | 150         | 30/0/15                  | 105                           | E               | 5  |       |          | AUT104        |
| AUT267   | Intelligent technology in robotics                                    | 2     | BD, CCH | 5                  | 150         | 30/0/15                  | 105                           | E               | 5  |       |          | AUT166        |
| MNG782   | Sustainable development strategies                                    | 2     | BD, CCH | 5                  | 150         | 30/0/15                  | 105                           | E               | 5  |       |          |               |
| CYCLE OF PROFILE DISCIPLINES (PD)                    |   |       |         |                    |             |                          |                               |                 |  |       |          |               |
| M-2. Module of theoretical foundations of management |   |       |         |                    |             |                          |                               |                 |  |       |          |               |
| AUT708   | Automation of engineering systems                                     |       | PD, UC  | 5                  | 150         | 30/0/15                  | 105                           | E               | 5  |       |          |               |
| AUT299   | Diagnostics of system automation                                      | 1     | PD, CCH | 5                  | 150         | 30/0/15                  | 105                           | E               |  | 5     |          |               |
| AUT700   | The reliability of the management system and its elements             | 1     | PD, CCH | 5                  | 150         | 30/0/15                  | 105                           | E               |  | 5     |          | AUT112        |
| AUT225   | Automation systems design   | 2     | PD, CCH | 5                  | 150         | 30/0/15                  | 105                           | E               |  | 5     |          | AUT166        |
| AUT707   | Distributed Control Systems   | 2     | PD, CCH | 5                  | 150         | 30/0/15                  | 105                           | E               |  | 5     |          | AUT268        |
| MNG705   | Project Management  | 2     | PD, CCH | 5                  | 150         | 30/0/15                  | 105                           | E               |  | 5     |          |               |
| M-3. Module of control system design                 |   |       |         |                    |             |                          |                               |                 |  |       |          |               |
| AUT709   | New information technologies  | 1     | PD, CCH | 5                  | 150         | 30/0/15                  | 105                           | E               | 5  |       |          |               |
| AUT285   | Modern executive devices of automation systems                        | 1     | PD, CCH | 5                  | 150         | 15/15/15                 | 105                           | E               | 5  |       |          | AUT108        |
| AUT714   | Machine Learning Algorithms in Technological Process Automation       | 2     | PD, CCH | 5                  | 150         | 30/15/0                  | 105                           | E               | 5  |       |          |               |
| AUT715   | Machine Learning Algorithms in Equipment Condition Diagnostic Systems | 2     | PD, CCH | 5                  | 150         | 30/15/0                  | 105                           | E               | 5  |       |          |               |
| AUT705   | Optimal control systems (with AI elements)                            | 1     | PD, CCH | 5                  | 150         | 30/0/15                  | 105                           | E               |  | 5     |          | AUT268        |
| AUT706   | Technical Vision system   | 1     | PD, CCH | 5                  | 150         | 30/0/15                  | 105                           | E               |  | 5     |          | AUT267        |
| AUT237   | Digital control systems   | 2     | PD, CCH | 5                  | 150         | 30/0/15                  | 105                           | E               |  | 5     |          | AUT102        |
| AUT251   | Dynamics of robot control   | 2     | PD, CCH | 5                  | 150         | 15/15/15                 | 105                           | E               |  | 5     |          | AUT104        |



**NJSC "Kazakh National RESEARCH Technical University"  
named after K.I. Satpayev"**

|  |  |   |         |    |     |         |     |   |           |    |           |        |
|--|--|---|---------|----|-----|---------|-----|---|-----------|----|-----------|--------|
| AUT701                                       | Automation of control systems design   | 3 | PD, CCH | 5  | 150 | 30/0/15 | 105 | E |           | 5  |           | AUT166 |
| AUT702                                       | Automated projection of robotic systems  | 3 | PD, CCH | 5  | 150 | 30/0/15 | 105 | E |           | 5  |           |        |
| AUT716                                       | Complex control systems  |   | PD, UC  | 4  | 120 | 30/0/15 | 75  | E |           |    | 4         |        |
| <b>M-4. Practice-oriented module</b>         |  |   |         |    |     |         |     |   |           |    |           |        |
| AAP248                                       | Internship   |   | PD, UC  | 5  |     |         |     | R |           | 5  |           |        |
| <b>M-5. Experimental and research module</b> |  |   |         |    |     |         |     |   |           |    |           |        |
| AAP249                                       | Experimental research work of a master student, including an internship and the implementation of a master's project |   | ERWMS   | 18 |     |         |     | R |           |    | 18        |        |
| <b>M-6. Module of final attestation</b>      |  |   |         |    |     |         |     |   |           |    |           |        |
| ECA213                                       | Design and defense of the master's project   |   | FA      | 8  |     |         |     |   |           |    | 8         |        |
| <b>Total based on UNIVERSITY:</b>            |  |   |         |    |     |         |     |   | 30        | 30 | 30        |        |
|  |  |   |         |    |     |         |     |   | <b>60</b> |    | <b>30</b> |        |

**Number of credits for the entire period of study**

| Cycle code                             | Cycles of disciplines                          | Credits                 |                           |                           |           |
|--|--|-------------------------|---------------------------|---------------------------|-----------|
|  |  | Required component (RC) | University component (UC) | Component of choice (CCH) | Total     |
| GED                                    | Cycle of general education disciplines         | 0                       | 0                         | 0                         | 0         |
| BD                                     | Cycle of basic disciplines                     | 0                       | 6                         | 9                         | 15        |
| PD                                     | Cycle of profile disciplines                   | 0                       | 14                        | 35                        | 49        |
| <b>Total for theoretical training:</b> |  | <b>0</b>                | <b>20</b>                 | <b>44</b>                 | <b>64</b> |
| RWMS                                   | Research Work of Master's Student              |                         |                           |                           | 0         |
| ERWMS                                  | Experimental Research Work of Master's Student |                         |                           |                           | 18        |
| FA                                     | Final attestation                              |                         |                           |                           | 8         |
| <b>TOTAL:</b>                          |  |                         |                           |                           | <b>90</b> |

**Decision of the Educational and Methodological Council of KazNRTU named after K.Satpayev. Minutes № 3 dated 20.12.2024**

**Decision of the Academic Council of the Institute. Minutes № 4 dated 22.11.2024**

**Signed:**

Governing Board member - Vice-Rector for Academic Affairs

Uskenbayeva R. K.

**Approved:**

Vice Provost on academic development

Kalpeyeva Z. B.

Head of Department - Department of Educational Program Management and Academic-Methodological Work

Zhumagaliyeva A. S.

acting Director of Institute - Institute of Automation and Information Technologies

Chiniybayev Y. I.

Department Chair - Automation and control

Sarsenbayev N. .

Representative of the Academic Committee from Employers

Saurambayev Z.

\_\_\_\_ Acknowledged \_\_\_\_



## 6. Additional educational programs (Minor)

| Name of additional educational programs (Minor) with disciplines | Total number of credits | Recommended semesters of study | Documents on the results of development additional educational programs (Minor) |
|--|-------------------------|--------------------------------|---|
|  |                         |                                |   |
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